



Custom Model Development

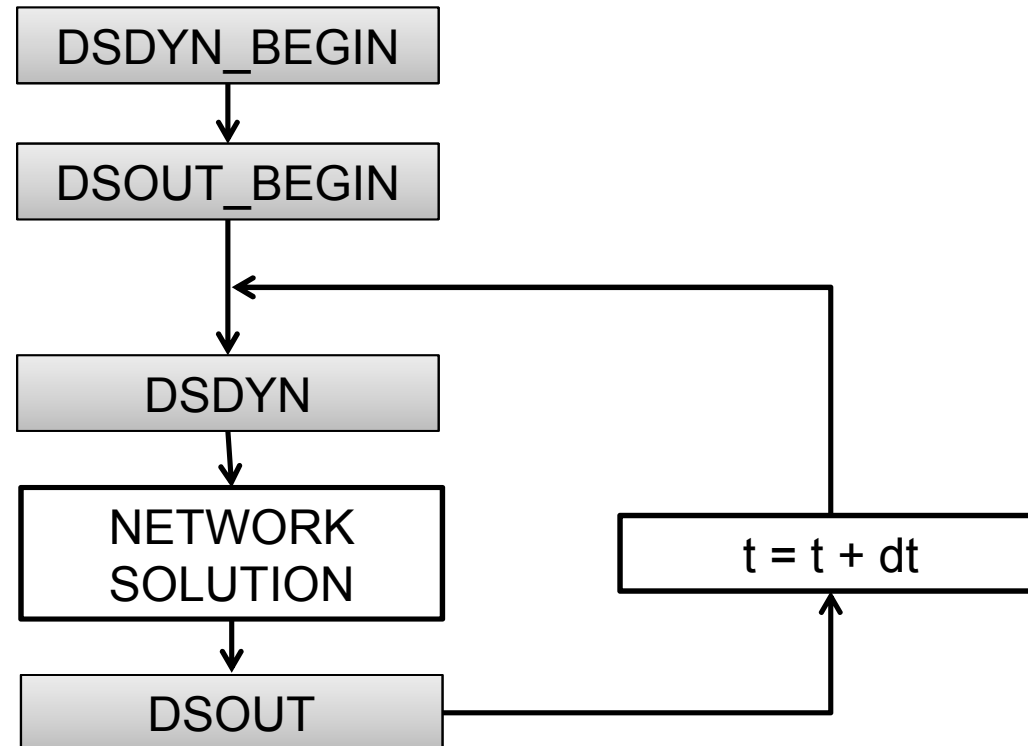
Rohitha Jayasinghe



Presentation Content

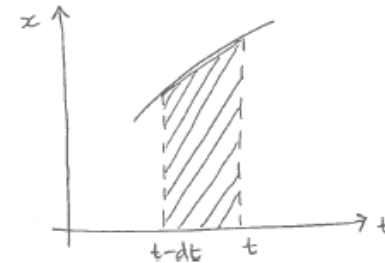
- Program structure of EMTDC
- How electrical circuit components and mathematical blocks are treated
- Numerical solution to differential equation
- Data storage and memory management
- Mathematical block example
- Representation of electrical elements
- Electrical element example

Program Structure



Solving Differential Equations Numerically

- Typically use trapezoidal rule



$$y = \int x dt$$

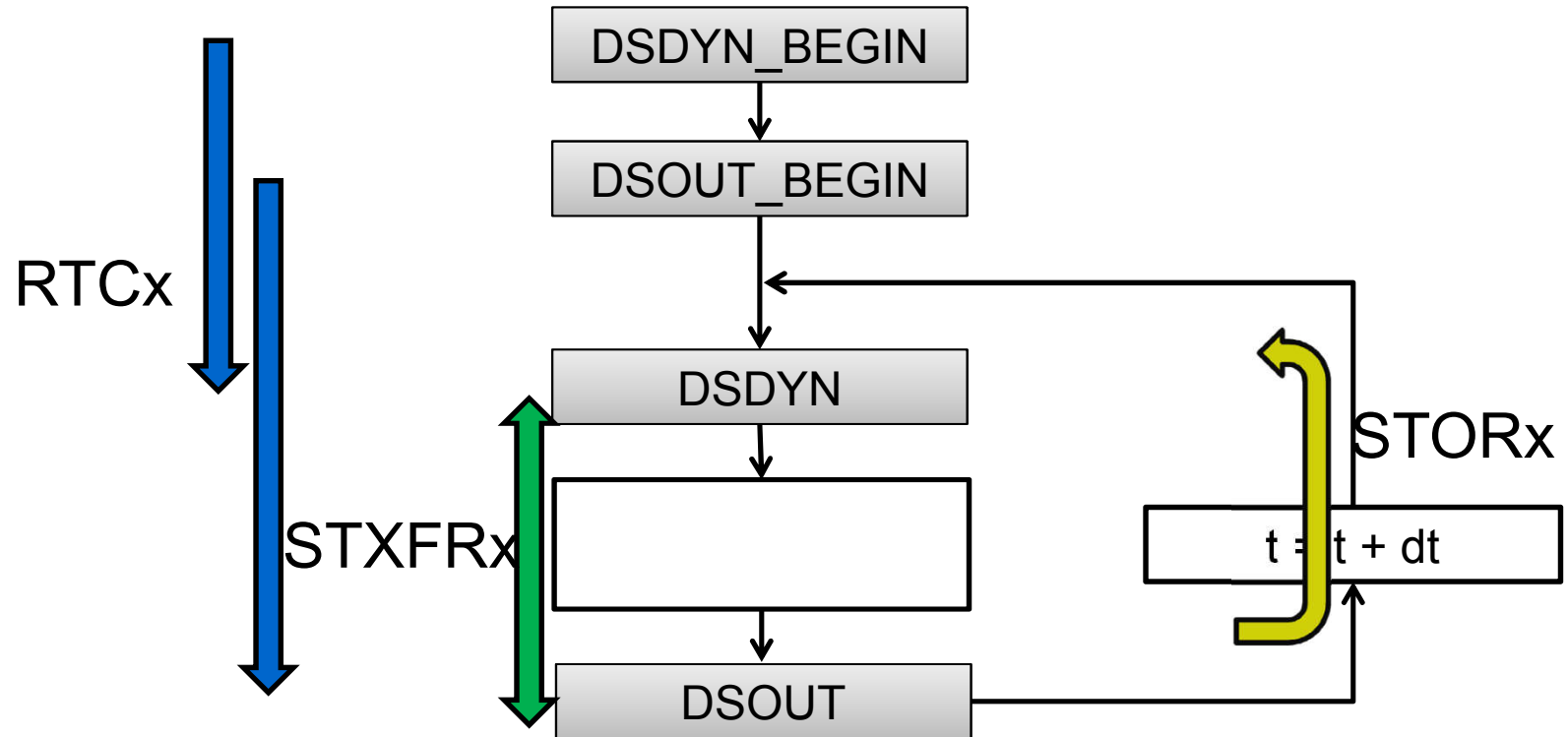
$$y(t) = y(t-dt) + \frac{x(t) + x(t-dt)}{2} dt$$

Data Storage & Memory Management

- STORx Arrays
 - Transfer data from time step to time step
- RTCx Arrays
 - Transfer data from DSDYN_BEGIN to DSDYN or DSOUT_BEGIN to DSOUT
- STXFRx Arrays
 - Transfer data from DSDYN to DSOUT or vice versa

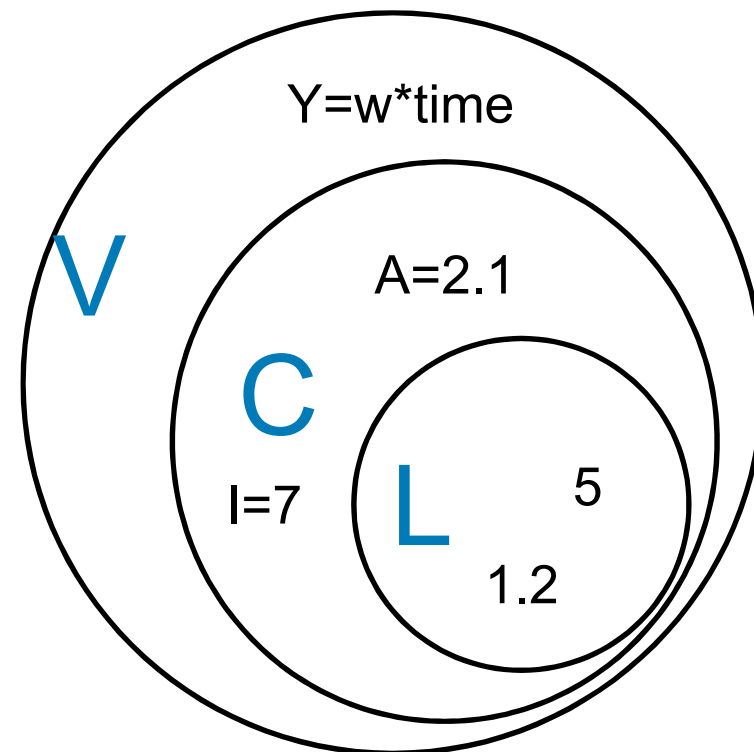
x = Logical, Integer, Floating point, Complex

Data Storage & Memory Management



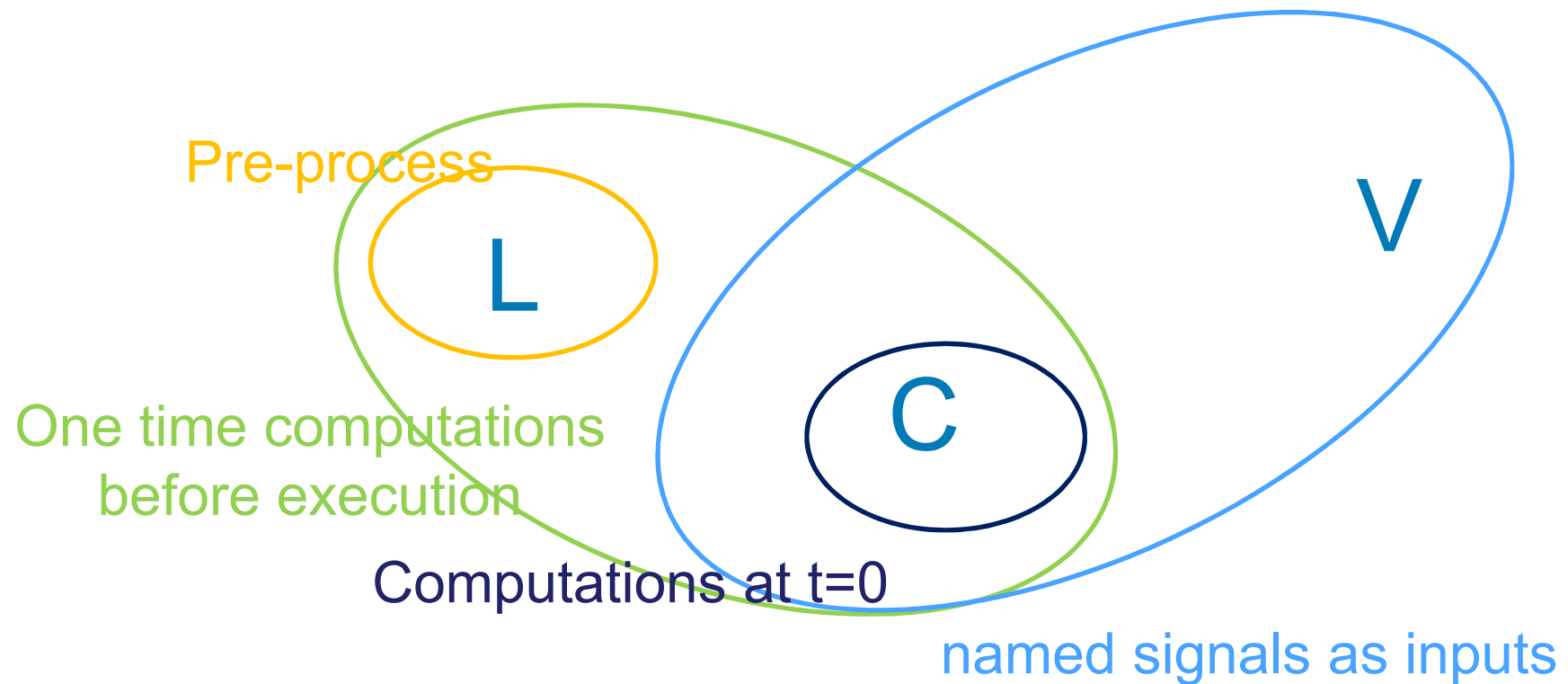
Parameter Data Types

- **Literal**
 - Could be used for pre-processing
- **Constant**
 - Could be used in one time computations in `_BEGIN` routines
 - Could be transferred from a page module parameter
- **Variable**
 - Executable code could become less efficient compared to other two





Parameter Data Types



Segment Types

- Branch
 - Electrical branches
- Checks
 - Checks based on literal or choice parameters
- Comments
- Computations
 - Computations based on literal or choice parameters
- Dsdyn/Dsout/Fortran
 - Code written to Fortran routines generated
 - Anything in between #BEGIN and #ENDBEGIN goes to _BEGIN routines
 - "Fortran" segment may go to either Dsdyn or Dsout

Segment Types

- FlyBy
 - FlyBy help text on port connections
- Help
 - Link to a help document
- Matrix-Fill
 - Information on how the matrix will be filled.
Helps to order the nodes
- Model-Data
 - Information written to data file
- Transformers
 - If transformers are used how they are connected.

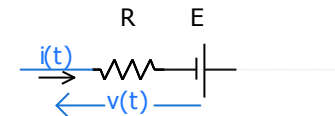
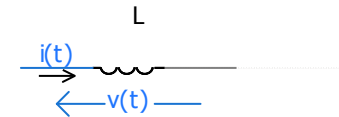
Example of an electrical branch Inductor as a custom component

$$v = L \frac{di}{dt}$$

$$\frac{v(t) + v(t + dt)}{2} = L \frac{i(t) + i(t + dt)}{dt}$$

$$v(t) = \frac{2L}{dt} i(t) + \frac{2L}{dt} i(t + dt) - v(t + dt)$$

$$v(t) = R i(t) + E(t)$$



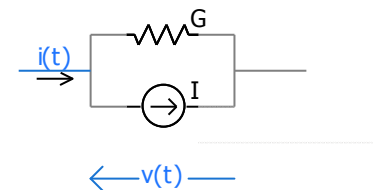
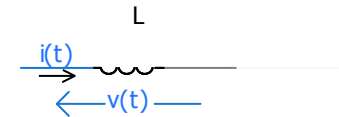
Example of an electrical branch Inductor as a custom component

$$v = L \frac{di}{dt}$$

$$\frac{v(t) + v(t + dt)}{2} = L \frac{i(t) + i(t + dt)}{dt}$$

$$i(t) = \frac{dt}{2L} v(t) + i(t + dt) + \frac{dt}{2L} v(t + dt)$$

$$i(t) = G v(t) + I(t)$$



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Thank you.

Questions: support@pscad.com