

MANITOBA HVDC RESEARCH CENTRE,
a Division of Manitoba Hydro International Ltd.

Machine Modeling and Power System Study Applications

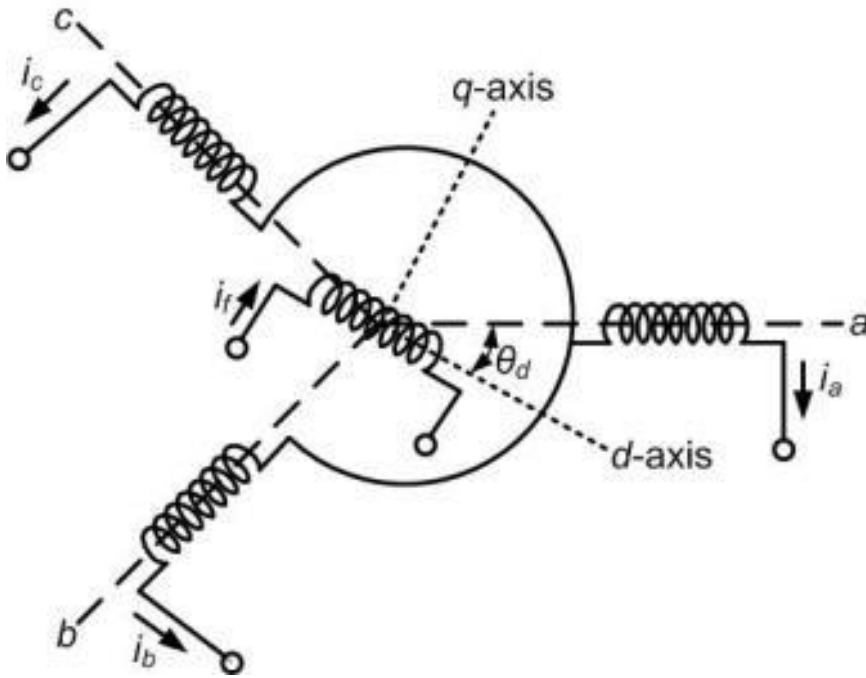
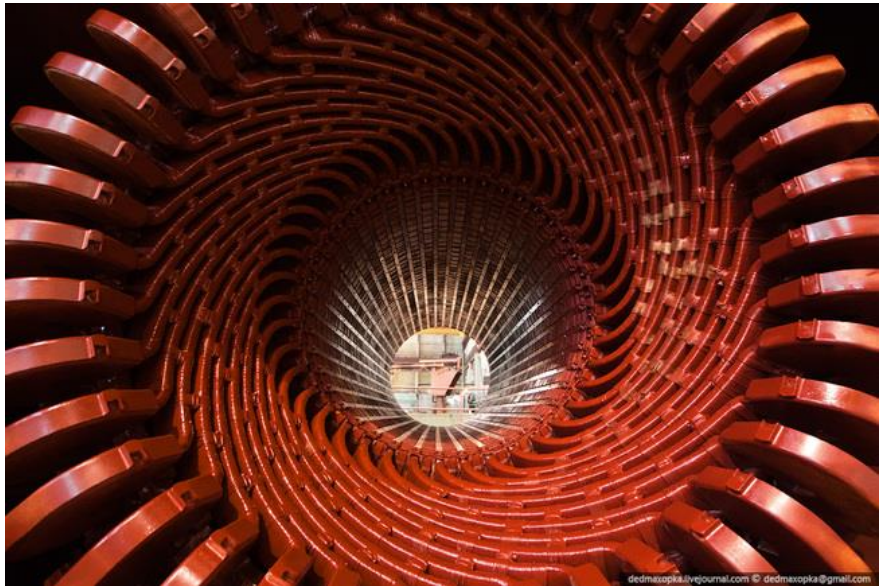
November 02, 2017

Presented by: Dharshana Muthumuni

Outline - Machine Modeling and Applications

- Mathematical representation of machine windings and rotor dynamics
- Machine models and controls models available in PSCAD
- Setting up a PSCAD simulation case
 - Synchronous machine (initialization of machine and control models)
 - Induction machine (starting example)
- Illustration of Simulation examples
 - Synchronous machine under black start conditions
 - Voltage flicker due to compressor load driven by a synchronous machine
 - Sub synchronous resonance and torsional interactions
 - Voltage dips due to induction motor starting and mitigation options
 - Applications in wind generation (DFIG)
 - Synchronous condenser application to improve wind farm FRT performance
 - PM machine in wind generation
- Internal faults simulation other enhancements to standard models

Machine windings and the mathematical representation



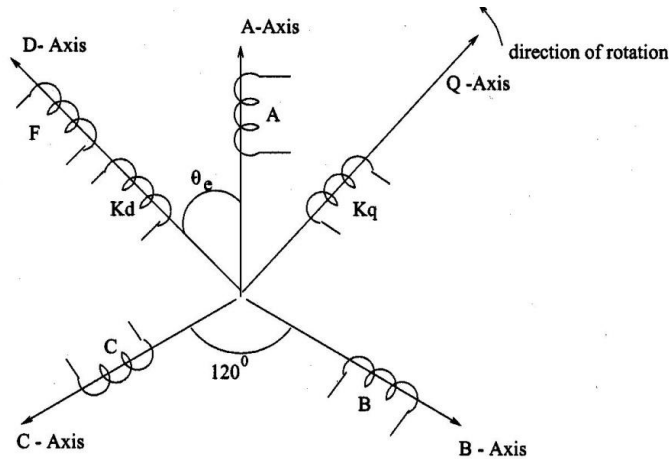


Figure 2.1: Representation of the machine coils and the direction of their magnetic axes

$$[v] = [R][i] + d/dt[L][i]$$



$$L_A = L_1 + L_2 + L_3 \cos(2\theta)$$

$$M_{AF} = f(\theta)$$

Synchronous Machine Equations in d-q reference frame

Stator Side

$$V_d = R_s \cdot i_d + \frac{d}{dt} \lambda_d(t) - \lambda_q(t) \cdot \omega_r$$

$$V_q = R_s \cdot i_q + \frac{d}{dt} \lambda_q(t) + \lambda_d(t) \cdot \omega_r$$

$$V_0 = R_0 \cdot i_0 + \frac{d}{dt} \lambda_0(t)$$

Rotor Side

$$E_f = R_f \cdot i_f + \frac{d}{dt} \lambda_f(t)$$

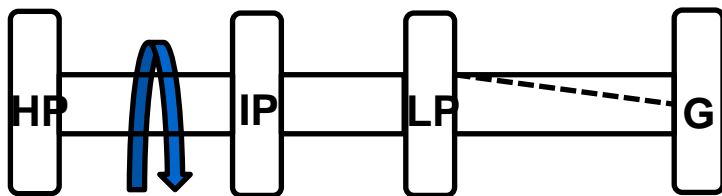
$$0 = R_{kd} \cdot i_{kd} + \frac{d}{dt} \lambda_{kd}(t)$$

$$0 = R_{kq1} \cdot i_{kq1} + \frac{d}{dt} \lambda_{kq1}(t)$$

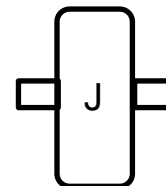
$$0 = R_{kq2} \cdot i_{kq2} + \frac{d}{dt} \lambda_{kq2}(t)$$

Dampers – 2 on Q-axis

Mechanical rotation

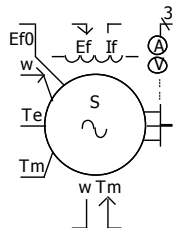


Speed - ω_k

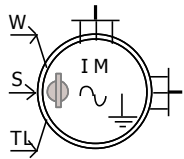


$$T_m - T_e = J \frac{d\omega}{dt} + B\omega$$

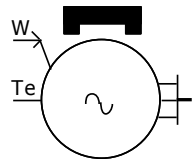
Machine Models in PSCAD



Synchronous Machine

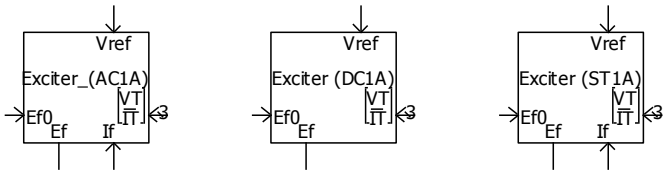


Induction Machine

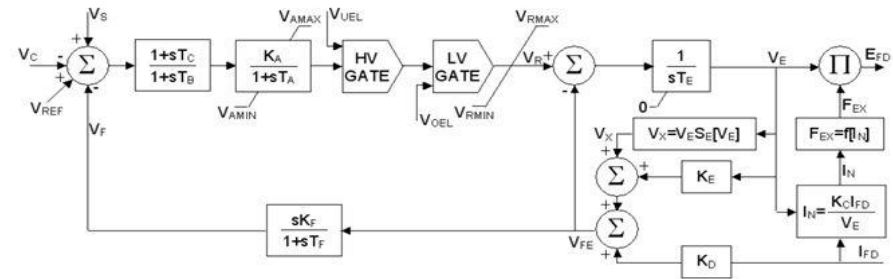


Permanent Magnet Machine

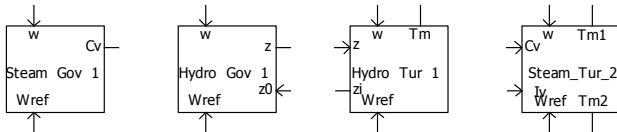
Exciter models



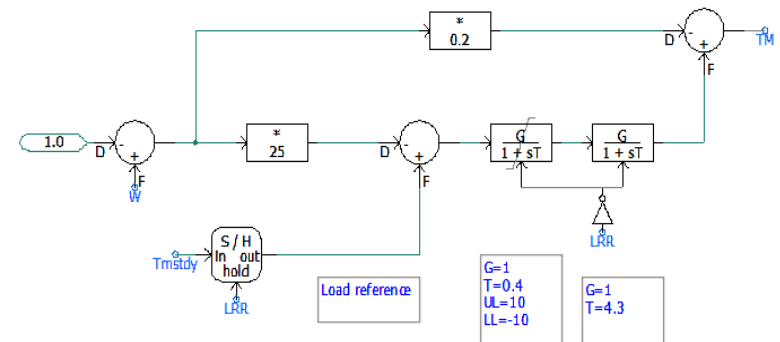
IEEE Standard exciter type AC1A



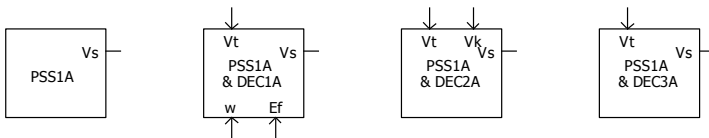
Governor/Turbine models



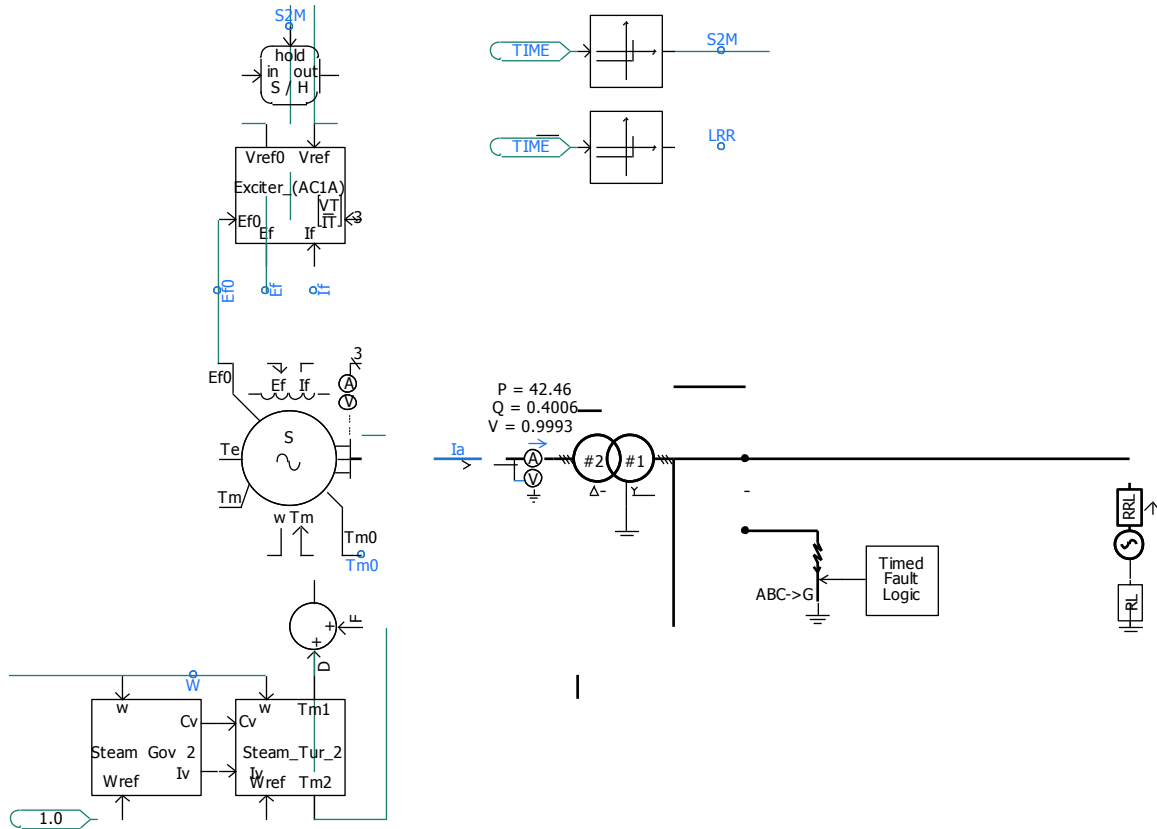
Non standard generator control systems



PSS models

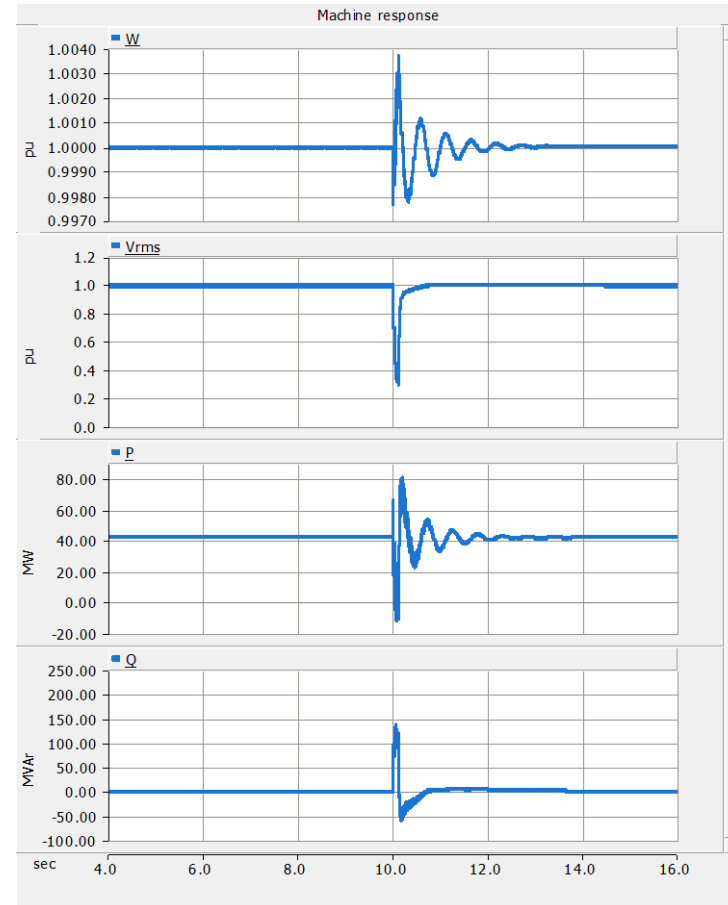
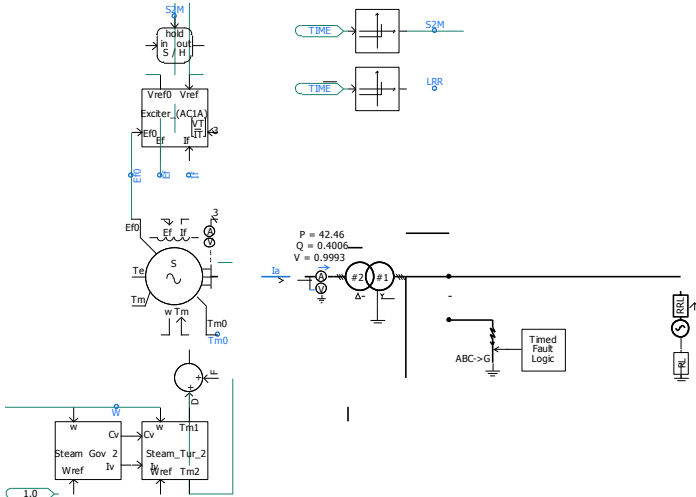


Simulation setup – Synchronous machine



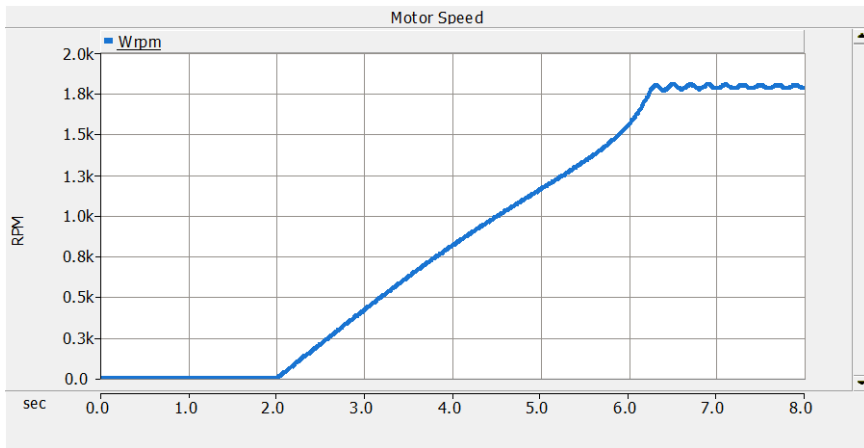
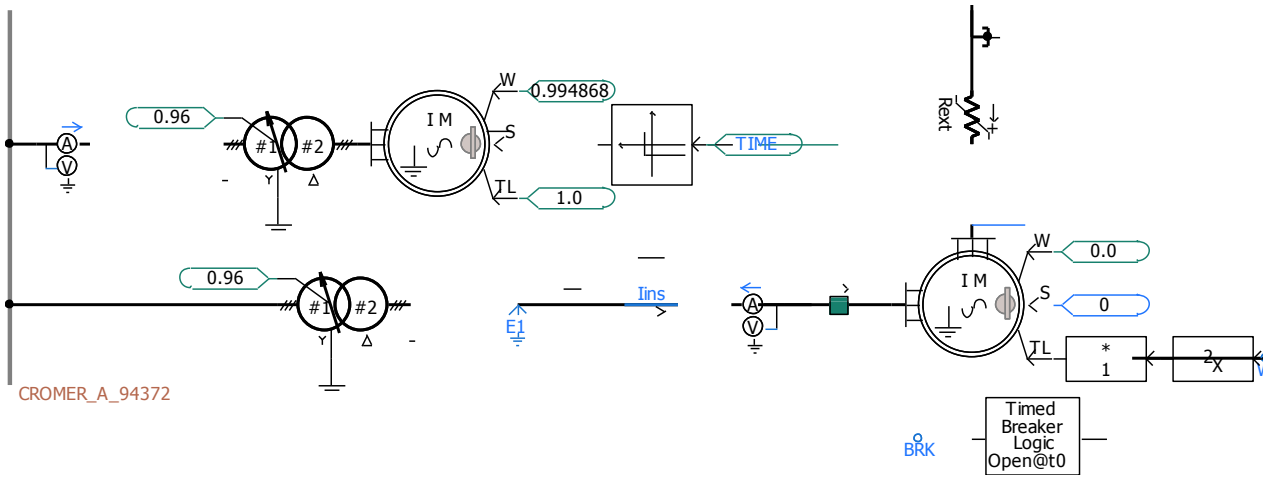
Parameter		Thermal units typical values
Sator leakage Inductance	X_l	0.1-0.2
Synchronous reactances	X_d	1.0-2.3
	X_q	1.0-2.3
Transient Reactance	X'_d	0.15-0.4
	X'_q	0.3-1.0
Subtransient Reactance	X''_d	0.12-0.25
	X''_q	0.12-0.25
Transient OC time constant	T'_{do}	3.0-10.0 s
	T'_{qo}	0.5-2.0 s
Subtransient OC Time constant	T''_{do}	0.02-0.05 s
	T''_{qo}	0.02-0.05 s

Simulation setup – Synchronous machine



Technical note available on how to set up the machine model and controls

Simulation setup – Induction machine



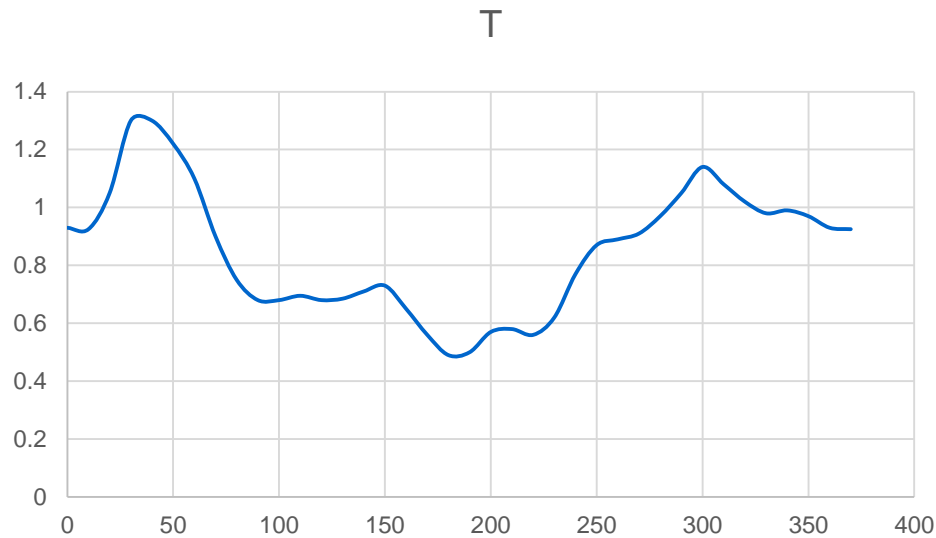
Technical note available on how to set up the machine model and controls

Simulation examples

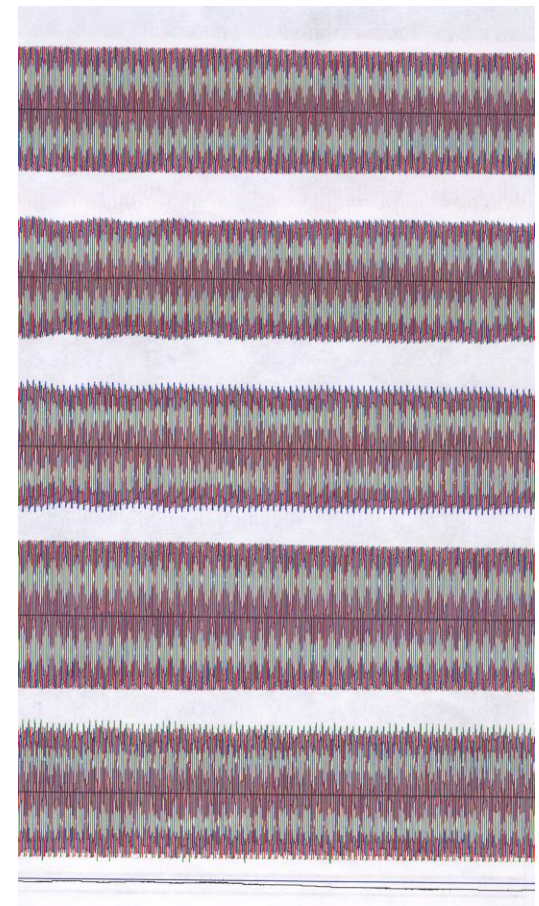
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Example: Flicker due to a synchronous motor driven compressor

Compressor load torque characteristics



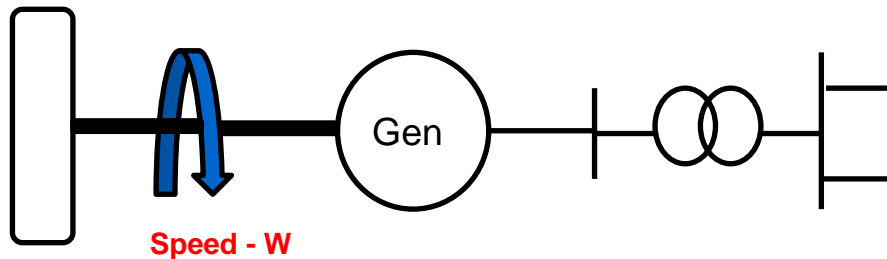
Voltage flicker measured at transmission level



Example: SSTI studies - Mechanical shaft-mass system

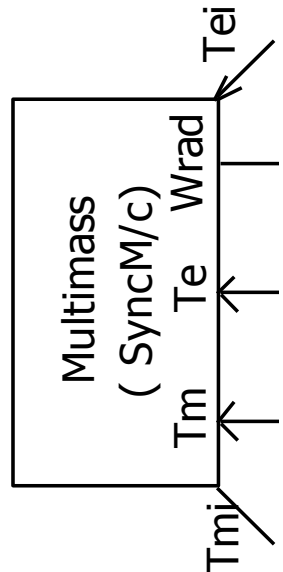
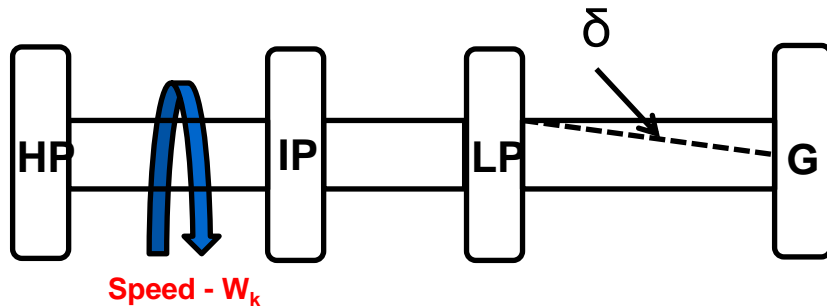


- Rotor of a Turbine Generator is a complex system of masses connected by shaft sections
- The total length can be as much as 50 m.



- A single lumped inertia representation is typically considered in system transient stability studies
 - Assumption: Rigid shafts

Mechanical shaft-mass system



- Torsional Interaction studies require a more detailed representation of the shaft (compared to lumped mass representation)
 - A **Multi-Mass** representation
 - Main rotor components represented as separate (rigid) masses
 - The masses are connected to each other with 'elastic' shaft sections

Thank you